

Q1. Gaussian Elimination.

$$\begin{cases} 4x + 2y + 3z = 0 \\ 2x + 5y + z = 9 \\ 3x + 2y + 6z = 6 \end{cases} \rightarrow \left[\begin{array}{ccc|c} 4 & 2 & 3 & 0 \\ 2 & 5 & 1 & 9 \\ 3 & 2 & 6 & 6 \end{array} \right]$$

Forward Elimination.1. Eliminate x from Row 2:

$$R_2 \leftarrow R_2 - \frac{1}{2}R_1 = R_2 - \frac{1}{2}R_1$$

$$R_2 = [2, 5, 1, 9] - \frac{1}{2}[4, 2, 3, 0] = [0, 4, -\frac{1}{2}, 6]$$

2. Eliminate x from Row 3:

$$R_3 \leftarrow R_3 - \frac{3}{4}R_1 = R_3 - 0.75R_1$$

$$R_3 = [3, 2, 6, 6] - \frac{3}{4}[4, 2, 3, 0] = [0, \frac{1}{2}, \frac{15}{4}, 6]$$

Now the matrix is...

$$\left[\begin{array}{ccc|c} 4 & 2 & 3 & 0 \\ 0 & 4 & -\frac{1}{2} & 6 \\ 0 & \frac{1}{2} & \frac{15}{4} & 6 \end{array} \right]$$

3. Eliminate y from Row 3 using

$$R_3 \leftarrow R_3 - \left(\frac{1}{8}\right)R_2 \text{ (factor } = \frac{\frac{1}{2}}{4} = \frac{1}{8})$$

$$R_3 = [0, \frac{1}{2}, \frac{15}{4}, 6] - \frac{1}{8}[0, 4, -\frac{1}{2}, 9]$$

$$= [0, 0, \frac{61}{16}, \frac{39}{8}]$$

Upper-triangular system...

$$\left[\begin{array}{ccc|c} 4 & 2 & 3 & 0 \\ 0 & 4 & -\frac{1}{2} & 6 \\ 0 & 0 & \frac{61}{16} & -\frac{39}{8} \end{array} \right]$$

Back substitution.

Row 3

$$\frac{61}{16}z = -\frac{39}{8} \Rightarrow z = \frac{\left(-\frac{39}{8}\right)}{\left(\frac{61}{16}\right)} = -\frac{78}{61}$$

Row 2.

$$4y - \frac{1}{2}z = 6 \Rightarrow y = \frac{6 + \frac{1}{2}z}{4} = \frac{6 + \frac{1}{2}\left(-\frac{78}{61}\right)}{4} = -\frac{147}{61}$$

Row 1

$$4x + 2y + 3z = 0 \Rightarrow x = \frac{-2y - 3z}{4} = \frac{522}{244}$$

$$= \frac{-2 \cdot \frac{147}{61} - 3 \cdot \frac{78}{61}}{4} = -\frac{132}{61}$$

Therefore,

$$x = -\frac{132}{61},$$

$$y = -\frac{147}{61},$$

$$z = -\frac{78}{61}$$

Q2) Augmented Matrix & Row Reduction.

$$\left[\begin{array}{ccc|c} 4 & 1 & 2 & 0 \\ 1 & 4 & 3 & 9 \\ 2 & 3 & 4 & 6 \end{array} \right]$$

a) Gaussian Elimination. (row operations)

$$R'_2 = 4 \cdot R_2 - 1R_1$$

$$= 4[1, 4, 3 | 9] - [4, 1, 2 | 0]$$

$$= [0, 15, 10 | 36]$$

$$R'_3 = 4R_3 - 2R_1$$

$$= 4[2, 3, 4 | 6] - 2[4, 1, 2 | 0]$$

$$= [0, 10, 12 | 24]$$

Eliminate y of R'_3 w/ R'_2

Since,

$$\begin{array}{lcl} A^2 - 1 = 16 - 1 & 3A - 2 = 12 - 2 \\ = 15 & = 10 \end{array}$$

So,

$$R''_3 = 15 \cdot R'_3 - 10 \cdot R'_2$$

$$= 15[0, 10, 12 | 24] - 10[0, 15, 10 | 36]$$

$$= [0, 0, 80 | 0]$$

Upper-triangular augmented matrix...

$$\left[\begin{array}{ccc|c} 4 & 1 & 2 & 0 \\ 0 & 15 & 10 & 36 \\ 0 & 0 & 80 & 0 \end{array} \right]$$

Verification by substitution.

$$4x + 1y + 2z = 4\left(-\frac{3}{5}\right) + \frac{12}{5} + 2 \cdot 0$$

$$= 0$$

$$= B$$

$$12x + 4y + 3z = -\frac{3}{5} + 4\left(\frac{12}{5}\right) + 0$$

$$= -\frac{3}{5} + \frac{48}{5}$$

$$= \frac{45}{5}$$

$$= 9$$

$$= C$$

b) Back substitution

Row 3.

$$80z = 0 \Rightarrow z = 0$$

Row 2.

$$15y + 10z = 36 \Rightarrow 15y = 36$$

$$\Rightarrow y = \frac{36}{15} = \frac{12}{5}$$

Row 1

$$4x + y + 2z = 0 \Rightarrow 4x + \frac{12}{5} = 0$$

$$\Rightarrow x = -\frac{12}{5} \cdot \frac{1}{4} = -\frac{3}{5}$$

So...

$$x = -\frac{3}{5} \quad z = 0$$

$$y = \frac{12}{5}$$

$$2x + 3y + 4z = 2\left(-\frac{3}{5}\right) + 3\left(\frac{12}{5}\right) + 0$$

$$= -\frac{6}{5} + \frac{36}{5}$$

$$= \frac{30}{5}$$

$$= 6$$

$$= D$$

Since

$(B, C, D) = (0, 9, 6)$ so solution is correct!

Q3) LU Decomposition.

$$A = \begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} 4 & 0 \\ 9 & 6 \end{bmatrix}, \quad b = \begin{bmatrix} A+B \\ C+D \end{bmatrix} = \begin{bmatrix} 4 \\ 15 \end{bmatrix}$$

a) Compute LU decomposition of A (no pivoting)

$$\text{We seek } L = \begin{bmatrix} 1 & 0 \\ l_{21} & 1 \end{bmatrix} \text{ \& } U = \begin{bmatrix} u_{11} & u_{12} \\ 0 & u_{22} \end{bmatrix} \text{ with } A = LU$$

$$u_{11} = a_{11} = 4$$

$$l_{21} = \frac{a_{21}}{u_{11}} = \frac{9}{4}$$

$$u_{12} = a_{12} = 0$$

$$u_{22} = a_{22} - l_{21}u_{12} = 6 - \left(\frac{9}{4}\right) \cdot 0 = 6$$

So

$$L = \begin{bmatrix} 1 & 0 \\ \frac{9}{4} & 1 \end{bmatrix}, \quad U = \begin{bmatrix} 4 & 0 \\ 0 & 6 \end{bmatrix} \text{ \& so } LU = \begin{bmatrix} 4 & 0 \\ 9 & 6 \end{bmatrix} = A$$

b) Solve $Ax = b$ using LU

$$\text{Solve } Ly = b$$

$$\begin{bmatrix} 1 & 0 \\ \frac{9}{4} & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 4 \\ 15 \end{bmatrix}$$

Forward substitution.

$$y_1 = 4$$

$$y_2 = 15 - \frac{9}{4} \cdot y_1$$

$$= 15 - \frac{9}{4} \cdot 4$$

$$= 15 - 9$$

$$= 6$$

Back substitution.

$$4x_1 = 4 \Rightarrow x_1 = 1$$

$$6x_2 = 6 \Rightarrow x_2 = 1$$

So

$$x = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Solve. Use $x = y$

$$\begin{bmatrix} 4 & 0 \\ 0 & 6 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 4 \\ 6 \end{bmatrix}$$

Verification.

$$Ax = \begin{bmatrix} 4 & 0 \\ 9 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 4 \\ 15 \end{bmatrix} = b$$

Correct!

Q4) Cholesky Decomposition.

$$A = \begin{bmatrix} A+4 & B \\ B & D+2 \end{bmatrix} = \begin{bmatrix} 4+4 & 0 \\ 0 & 6+2 \end{bmatrix} = \begin{bmatrix} 8 & 0 \\ 0 & 8 \end{bmatrix}, \quad b = \begin{bmatrix} B \\ D \end{bmatrix} = \begin{bmatrix} 0 \\ 6 \end{bmatrix}$$

a) Verify if A is a positive definite.

Since... A is symmetric... & both principle minors are positive,
 $m_1 = 8 > 0$
 $\det(A) = 8 \cdot 8 - 0 = 64 > 0$
 so A is positive definite.

b) If so, compute the Cholesky factorization $A = LL^T$
 Since A is diagonal with equal entries, the Cholesky factor is diagonal with square roots on the diagonal.

$$L = \begin{bmatrix} \sqrt{8} & 0 \\ 0 & \sqrt{8} \end{bmatrix} = \begin{bmatrix} 2\sqrt{2} & 0 \\ 0 & 2\sqrt{2} \end{bmatrix}$$

Check LL^T
 $= \text{diag}((\sqrt{8})^2, (\sqrt{8})^2) = \text{diag}(8, 8) = A.$

c) Solve $Ax = b$ using Cholesky

Solve $Ly = b$ then $L^T x = y$

1. $Ly = b$

$$\begin{bmatrix} 2\sqrt{2} & 0 \\ 0 & 2\sqrt{2} \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 6 \end{bmatrix} \Rightarrow y_1 = 0, y_2 = \frac{6}{2\sqrt{2}} = \frac{3}{\sqrt{2}}$$

2. $L^T x = y$ (but $L^T = L$) here

$$\begin{bmatrix} 2\sqrt{2} & 0 \\ 0 & 2\sqrt{2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{3}{\sqrt{2}} \end{bmatrix} \Rightarrow x_1 = 0, x_2 = \frac{\frac{3}{\sqrt{2}}}{2\sqrt{2}} = \frac{3}{4}$$

So

$$x = \begin{bmatrix} 0 \\ \frac{3}{4} \end{bmatrix}$$

Check:

$$Ax = 8 \cdot \begin{bmatrix} 0 \\ \frac{3}{4} \end{bmatrix}^T$$

$$= \begin{bmatrix} 0 \\ 6 \end{bmatrix}^T$$

$$= b$$

Q5. Limit of matrix powers.

$$\text{Let } M = \begin{bmatrix} 0.4 & 0.0 \\ 0.9 & 0.6 \end{bmatrix}$$

a) Compute the eigenvalues of M .

Since M is lower triangular, its eigenvalues are the diagonal entries.

$$\lambda_1 = 0.4, \quad \lambda_2 = 0.6.$$

b) Determine whether $\lim(M^n)$ as $n \rightarrow \infty$ exists.

Yes, both eigenvalues have absolute value < 1 .

For any square matrix, if $\rho(M) < 1$ then $M^n \rightarrow 0$ as $n \rightarrow \infty$.

So the limit exists.

c) The limit and why it converges.

Limit is zero matrix.

$$\lim_{n \rightarrow \infty} M^n = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

Since $|\lambda_i| < 1$, powers of the eigenvalues go to zero; more generally

$\|M^n\| \leq C \cdot \rho(M)^n$ for some constant C , so $M^n \rightarrow 0$.

Distinct eigenvalues here also imply M is diagonalizable, but diagonalizability is not required for the conclusion: spectral radius < 1 suffices.

Because M is lower triangular with a zero in the $(1, 2)$ entry, we can

$$M^n = \begin{bmatrix} 0.4^n & 0 \\ 0.9 \sum_{k=0}^{n-1} 0.4^{n-1-k} 0.6^k & 0.6^n \end{bmatrix} = \begin{bmatrix} 0.4^n & 0 \\ 4.5(0.6^n - 0.4^n) & 0.6^n \end{bmatrix}$$

every entry tends to 0 as $n \rightarrow \infty$.

Bonus: QR Factorization.

$$A = \begin{bmatrix} 4 & 0 \\ 9 & 6 \end{bmatrix}$$

a) Compute via Gram-Schmidt

Let columns be

$$a_1 = \begin{bmatrix} 4 \\ 9 \end{bmatrix}, \quad a_2 = \begin{bmatrix} 0 \\ 6 \end{bmatrix}$$

Compute $u_1 = a_1$ & its norm

$$\|a_1\| = \sqrt{4^2 + 9^2}$$

$$= \sqrt{16 + 81}$$

$$= \sqrt{97}$$

Project a_2 into q_1 :

$$\text{proj}_{q_1}(a_2) = (q_1^T a_2) q_1 \text{ with } q_1^T a_2 = \frac{1}{\sqrt{97}} (4 \cdot 0 + 9 \cdot 6) = \frac{54}{\sqrt{97}}$$

Thus

$$\begin{aligned} \text{proj}_{q_1}(a_2) &= \frac{54}{\sqrt{97}} q_1 \\ &= \frac{54}{97} \begin{bmatrix} 4 \\ 9 \end{bmatrix} \\ &= \begin{bmatrix} \frac{216}{97} \\ \frac{486}{97} \end{bmatrix} \end{aligned}$$

Form the second orthogonal vector:

$$u_2 = a_2 - \text{proj}_{q_1}(a_2) = \begin{bmatrix} 0 \\ 6 \end{bmatrix} - \begin{bmatrix} \frac{216}{97} \\ \frac{486}{97} \end{bmatrix} = \frac{1}{97} \begin{bmatrix} -216 \\ 582 \end{bmatrix}$$

Its norm is.

$$\|u_2\| = \frac{24}{97} \sqrt{(-9)^2 + 4^2}$$

$$= \frac{24}{97} \sqrt{97}$$

$$= \frac{24}{\sqrt{97}}$$

So, second unit vector is

$$q_2 = \frac{u_2}{\|u_2\|} = \frac{\frac{24}{97} \begin{bmatrix} -9 \\ 4 \end{bmatrix}}{\frac{24}{\sqrt{97}}} = \frac{1}{\sqrt{97}} \begin{bmatrix} -9 \\ 4 \end{bmatrix}$$

The Q matrix.

Put q_1, q_2 as columns:

$$Q = (q_1, q_2)$$

$$= \frac{1}{\sqrt{97}} \begin{bmatrix} 4 & -9 \\ 9 & 4 \end{bmatrix}$$

The R matrix.

Using $R = Q^T A$ or the Gram-Schmidt scalars.

$$r_{11} = \|a_1\| = \sqrt{97}; \quad r_{12} = q_1^T a_2 = \frac{54}{\sqrt{97}}; \quad r_{22} = \|u_2\| = \frac{24}{\sqrt{97}}$$

& $r_{21} = 0$ Thus,

$$R = \begin{bmatrix} \sqrt{97} & \frac{54}{\sqrt{97}} \\ 0 & \frac{24}{\sqrt{97}} \end{bmatrix} \xrightarrow{\text{scale.}} \frac{1}{\sqrt{97}} \begin{bmatrix} 4 & -9 \\ 9 & 4 \end{bmatrix} \begin{bmatrix} \sqrt{97} & \frac{54}{\sqrt{97}} \\ 0 & \frac{24}{\sqrt{97}} \end{bmatrix}$$

$A = QR$.

b) Verify $Q^T Q = I$

compute.

$$Q^T Q = \frac{1}{97} \begin{bmatrix} 4 & 9 \\ -9 & 4 \end{bmatrix} \begin{bmatrix} 4 & -9 \\ 9 & 4 \end{bmatrix} = \frac{1}{97} \begin{bmatrix} 97 & 0 \\ 0 & 97 \end{bmatrix} = I_2$$

So Q is orthogonal.

c) Explain how QR can be used to solve $Ax = b$.

If $A = QR$ with orthogonal Q & upper-triangular invertible R , then

$$Ax = b \Rightarrow QRx = b$$

multiply both sides by Q^T (since $Q^T Q = I$)

$$Rx = Q^T b$$

Because R is upper triangular.

solve $Rx = Q^T b$ by back substitution. (efficient & numerically stable)

Via...

- Compute $y = Q^T b$ then solve the triangular system $Rx = y$ for x via back-substitution